

Formulation and calculation of isoparametric finite element matrixes

1. Numerical integration
2. Implementation of a finite element computer code

Gilles Richner

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Numerical integration

Goal: Integration of the matrix $F(r)$

Numerical integration

$$\int_a^b F(r) dr = \sum_i \alpha_i F(r_i)$$

With $a=-1$ and $b=1$ (isoparametric elements)

Approximation of $F(r)$ with $\psi(r)$

Polynomial:

$$\psi(r) = a_0 + a_1 r + a_2 r^2 + \dots + a_n r^n$$

Lagragian interp. :

$$\psi(r) = F_0 l_0(r) + F_1 l_1(r) + F_2 l_2(r) + \dots + F_n l_n(r)$$

With

$$l_j(r) = \frac{(r - r_0)(r - r_1) \cdots (r - r_{j-1})(r - r_{j+1}) \cdots (r - r_n)}{(r_j - r_0)(r_j - r_1) \cdots (r_j - r_{j-1})(r_j - r_{j+1}) \cdots (r_j - r_n)}$$

Numerical integration II

Newton: equally spaced sampling points

$$\int_a^b F(r) dr = (b - a) \sum_{i=0}^n C_i^n F(r_i) \quad \text{With } C_i^n = \text{Newton-Cotes constant}$$

Gauss: variation of sampling interval

$$\int_a^b F(r) dr = \sum_i \alpha_i F(r_i) \quad \text{With } \alpha_i = \int_{-1}^1 l_j(r) dr$$

Multidimensional integration

$$\int_{-1}^1 \int_{-1}^1 \int_{-1}^1 F(r, s, t) dr ds dt = \sum_{i, j, k} \alpha_i \alpha_j \alpha_k F(r_i, s_j, t_k)$$

Numerical integration III

Kind and order of integration

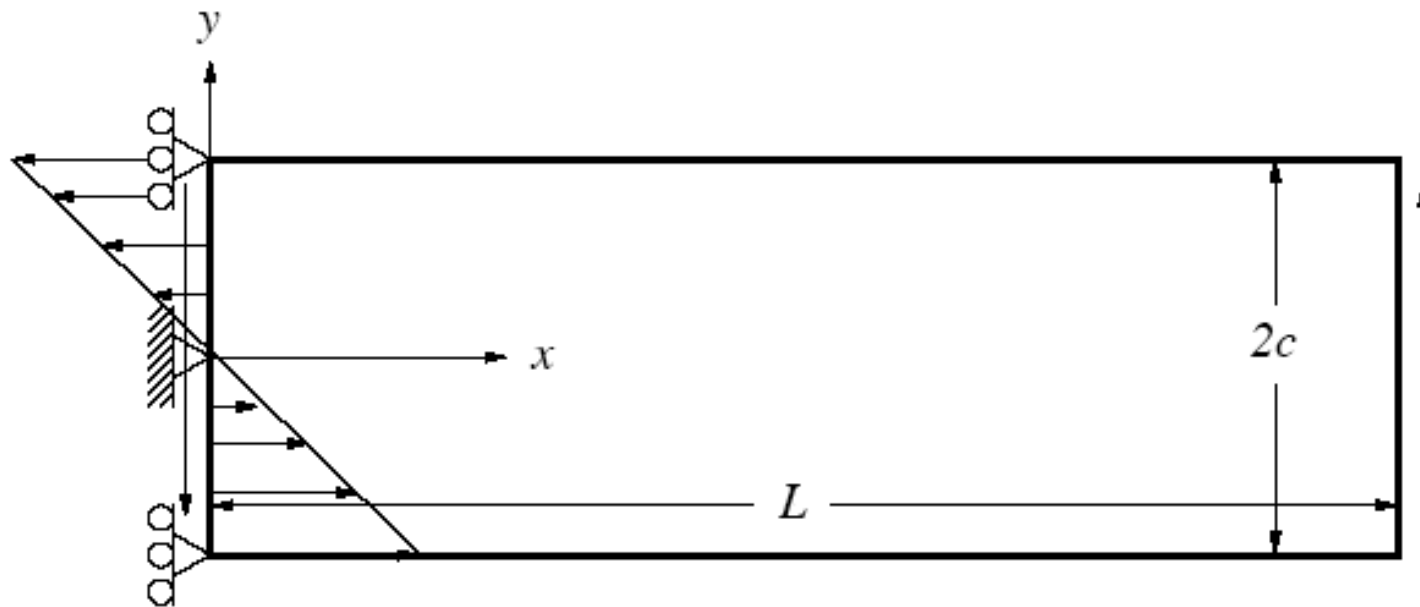
- => cost of analysis, errors, degree of local variables, linearity, ...
- => For displacement matrix => full integration

Reduced and Selective

- => Improving overall results by reducing the order of certain matrix evaluation
- => Different strains terms integrated with different orders

=> Stability and convergence

Example for FEM code



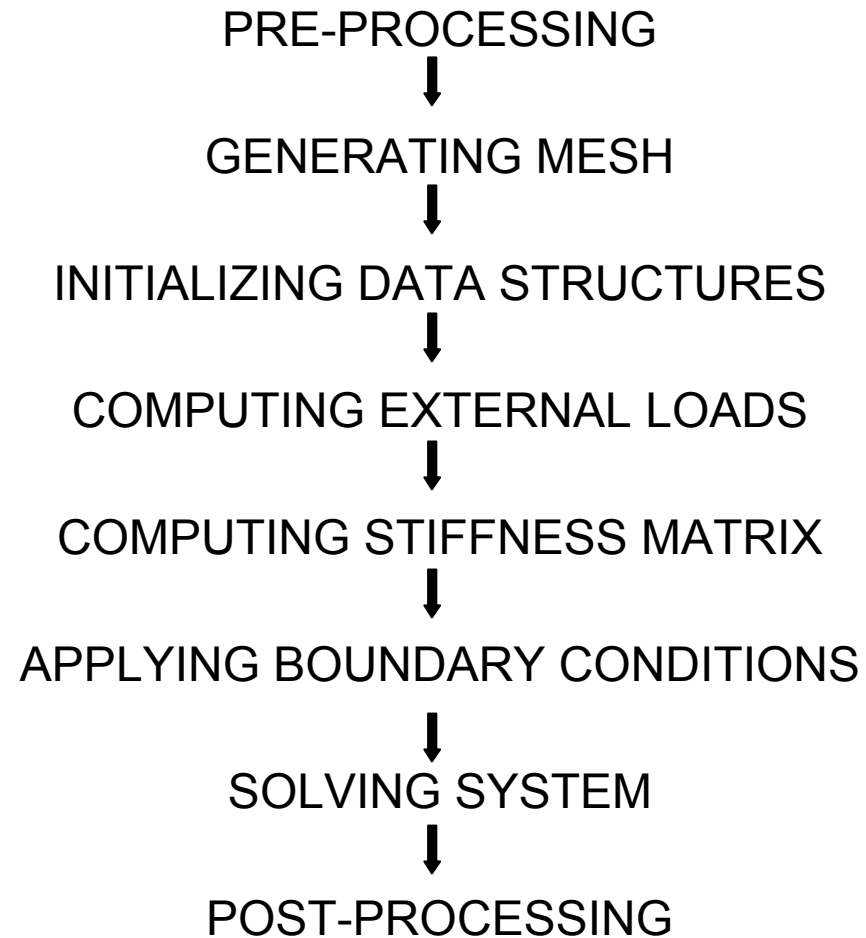
Displacement boundary conditions:

$u_x = 0$ @ $(0; c)$, $(0,0)$ and $(0; -c)$, $u_y = 0$ @ $(0; 0)$.

Traction boundary conditions:

$t_x = y$ on $x = 0$ and $t_y = P(x^2 - c^2)$ on $x = L$.

Implementation of computer code



Implementation of computer code II

PRE-PROCESSING

GENERATING MESH

INITIALIZING
DATA STRUCTURES

COMPUTING
EXTERNAL LOADS

COMPUTING
STIFFNESS MATRIX

APPLYING BOUNDARY
CONDITIONS

SOLVING SYSTEM

POST-PROCESSING

- **Material properties**
- **Beam properties**
- **Mesh properties**
- **Model assumption**

Implementation of computer code III

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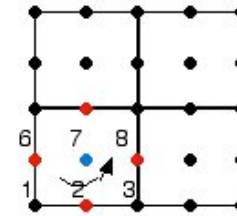
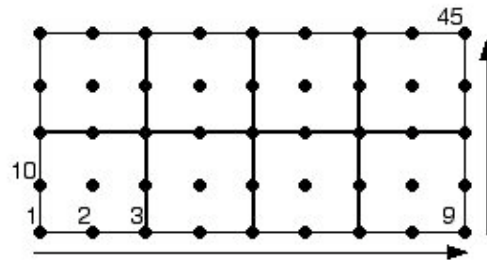
COMPUTING
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POST-PROCESSING

➤ Element connectivity matrix: Node pattern



➤ Boundary node pattern

➤ Displacement boundary

Implementation of computer code IV

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➤ Nodal displacement vector

```
U=zeros(2*numnode,1);
```

➤ External load vector

```
f=zeros(2*numnode,1);
```

➤ Stiffness matrix

```
K=sparse(2*numnode,2*numnode);
```

With numnode = total # nodes

Implementation of computer code V

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➤ Gaussian quadrature

```
[W,Q]=quadrature( 4, 'GAUSS', 1 );
```

Where W and Q are the sampling points and weights

➤ Shape function

```
[N,dNdx]=lagrange_basis(edgeElemType,pt);
```

➤ Integration of the tractions on the left and right edges

```
f(sctrx)=N*fxPt*detJ0*wt
```

With $fxPt$ = x traction at quadrature point

Implementation of computer code VI

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➤ Shape function

```
[W,Q]=quadrature( 4, 'GAUSS', 2 );
```

```
[N,dNdx]=lagrange_basis(edgeElemType,pt);
```

```
J0=node(sctr,:)'*dNdx;
```

```
dNdx=dNdx*invJ0;
```

➤ Compute Element Stiffness at quadrature point

```
K(sctrB,sctrB)=B'*C*B*W(q)*det(J0)
```

Implementation of computer code VII

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**APPLYING BOUNDARY
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Enforcement of the essential boundary conditions

Modifying the system but keeping it symmetric so that the boundary condition are satisfied according to the applied mapping.

Implementation of computer code VIII

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➤ Solving system

$$U=K \setminus f$$

➤ Compute Element strain and stress at the stress point

$$\text{strain}=B*U(\text{sctr}B);$$
$$\text{stress}(e,q,:)=C*\text{strain};$$

Literature

Code:

<http://www.tam.northwestern.edu/jfc795/Matlab/>

The finite element method, O.C. Zienkiewicz, R.L. Taylor - Butterworth
Heinemann (2000) Vol.1-3

Additional:

Matlab guide to finite elements: an interactive approach, (2005) P.I. Kattan

Introduction to finite and spectral element methods using Matlab,(2003)
C. Pozrikidis

The finite element method using Matlab (2000), Y.W. Kwon, H. Bang