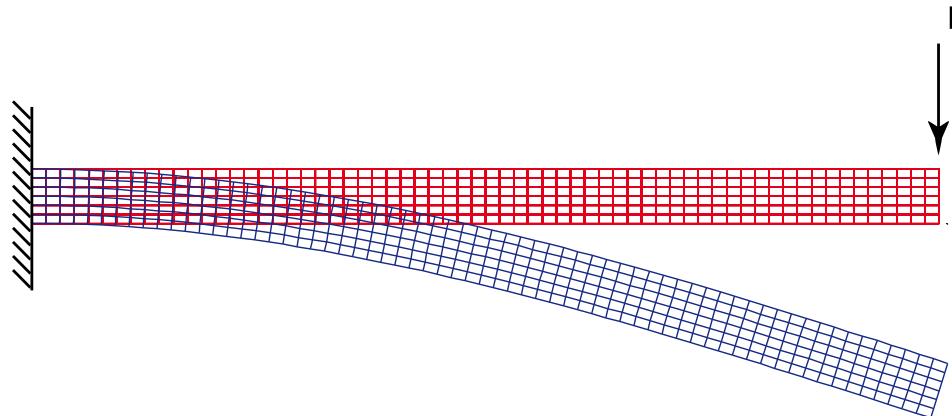


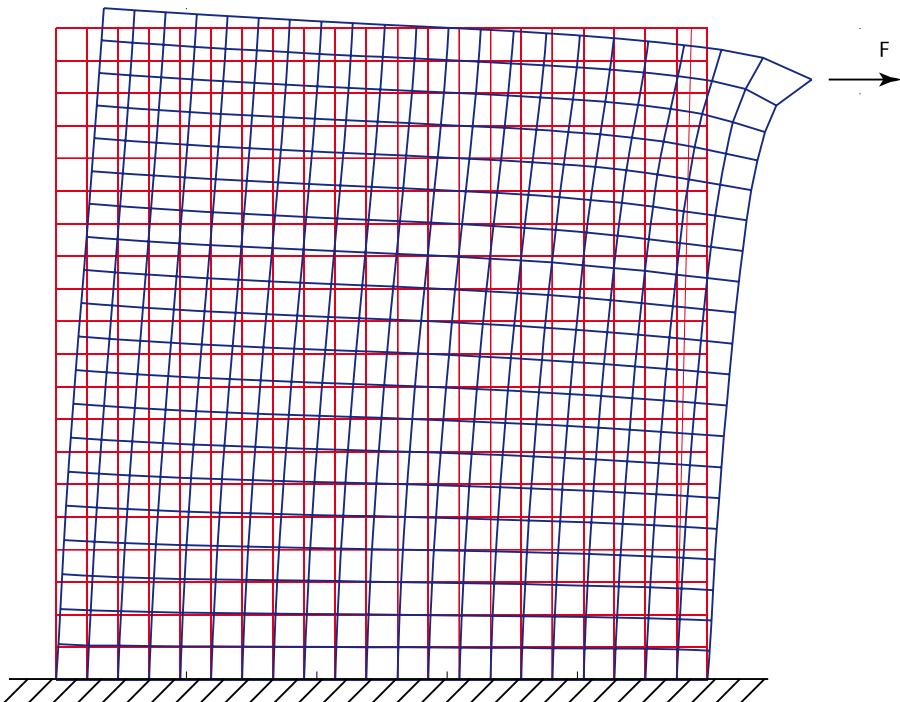
The Finite Element Method and the Analysis of Systems with Uncertain Properties



Example "4 Node Isoparametric Element"
PhD Seminar
Matthias Schubert

Group Risk and Safety
ETH – Zürich
10.01.07

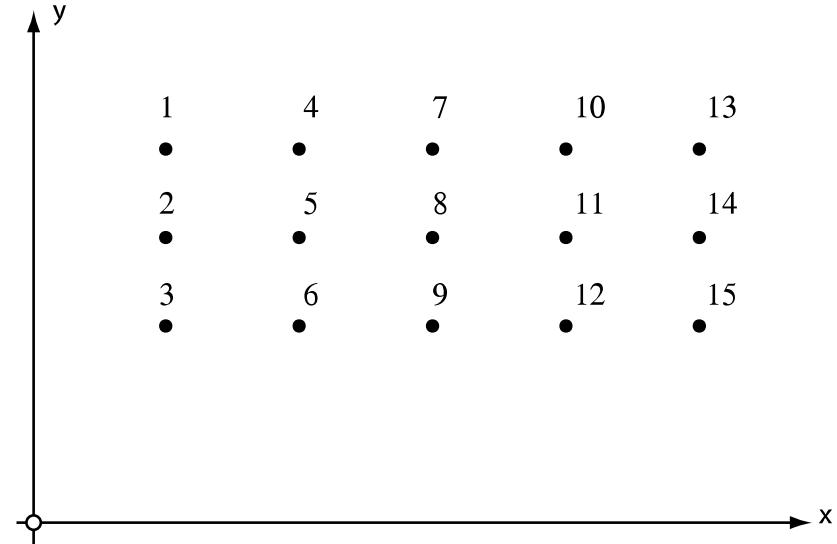
Overview



- Defining nodes / Geometry
- Assembling Elements
- Isoparametric 4 node elements
- The local stiffness matrix
- Assembling global stiffness matrix
- Convergence and results

Defining nodes / Geometry and Elements

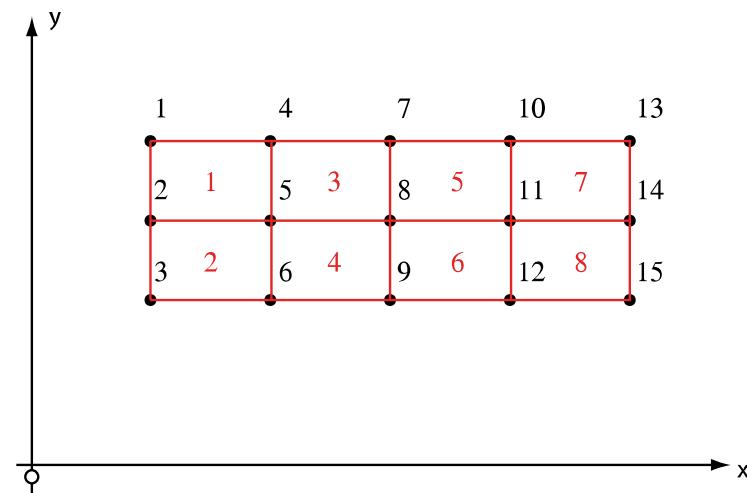
- An efficient node numbering reduces the bandwidth of the stiffness matrix



- The elements can now be defined using the node numbering

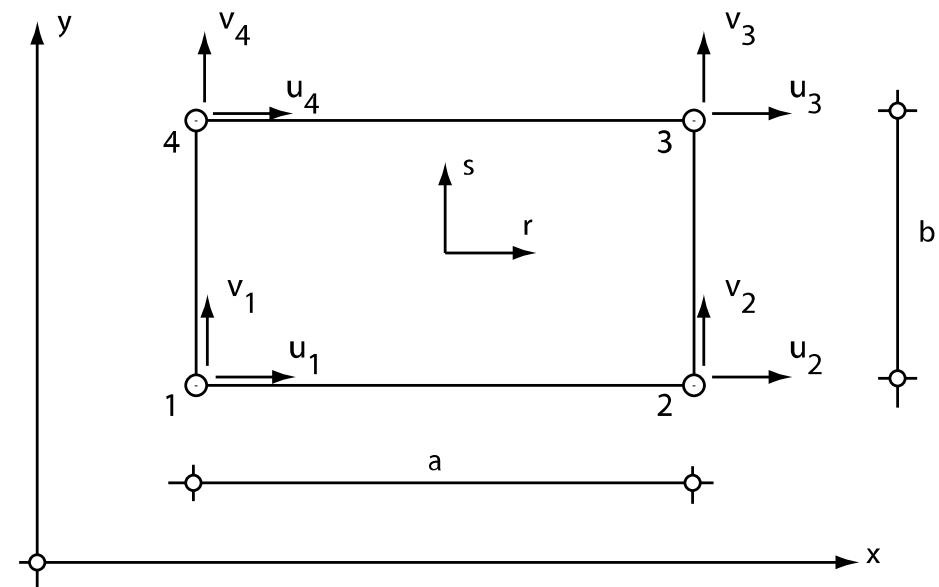
Element 1 = [1 4 5 2]

- Each node has two degrees of freedom



4 Node Isoparametric Elements

- Here: rectangular bilinear element
- rectangular
- 4 Nodes
- 8 Degrees of freedom



4 Node Isoparametric Elements

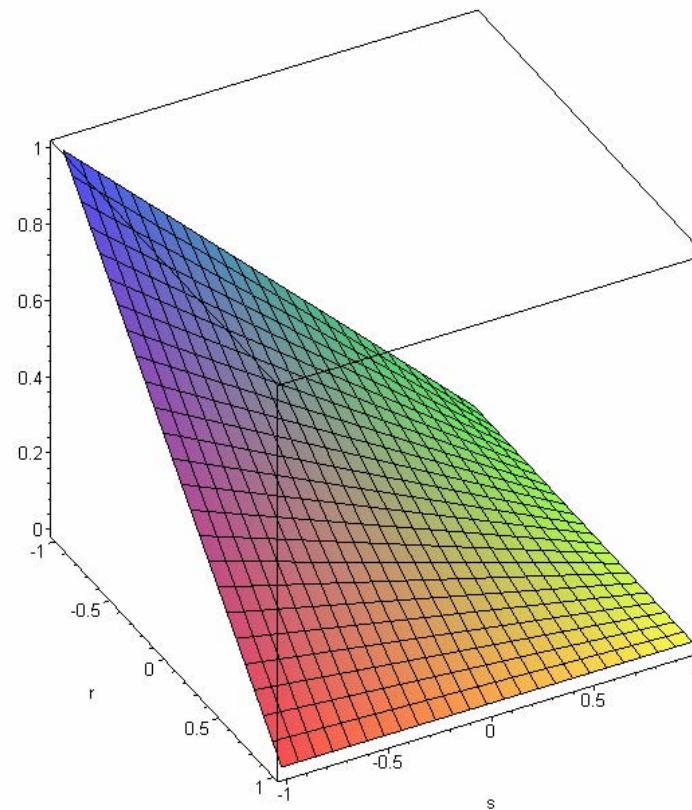
→ Bilinear shape function

$$\Omega_1 = \frac{1}{4}(1-r)(1-s)$$

$$\Omega_2 = \frac{1}{4}(1+r)(1-s)$$

$$\Omega_3 = \frac{1}{4}(1+r)(1+s)$$

$$\Omega_4 = \frac{1}{4}(1-r)(1+s)$$



4 Node Isoparametric Elements

Strain-displacement matrix B

$$\mathbf{B} = \mathbf{D}_k \boldsymbol{\Omega} = \begin{bmatrix} dx & 0 \\ 0 & dy \\ dy & dx \end{bmatrix} \begin{bmatrix} \Omega_1 & 0 & \Omega_2 & 0 & \Omega_3 & 0 & \Omega_4 & 0 \\ 0 & \Omega_1 & 0 & \Omega_2 & 0 & \Omega_3 & 0 & \Omega_4 \end{bmatrix}$$

$$\mathbf{B} = \frac{1}{4ab} \begin{bmatrix} -b(1-s) & 0 & b(1-s) & 0 & b(1+s) & 0 & -b(1+s) & 0 \\ 0 & -a(1-r) & 0 & -a(1+r) & 0 & a(1+r) & 0 & a(1-r) \\ -a(1-r) & -b(1-s) & -a(1+r) & b(1-s) & a(1+r) & b(1+s) & a(1-r) & -b(1+s) \end{bmatrix}$$

Stress-strain matrix E – usually constant in elastic problems

$$\mathbf{E} = \frac{Et}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & 0.5(1-\nu) \end{bmatrix}$$

The local stiffness matrix

$$\mathbf{k} = \int_{-1}^1 \int_{-1}^1 \mathbf{B}^T \mathbf{E} \mathbf{B} \frac{ab}{4} dr ds$$

In this case the stiffness matrix can be expressed in closed form

- numerical integration
- analytically

The local stiffness matrix

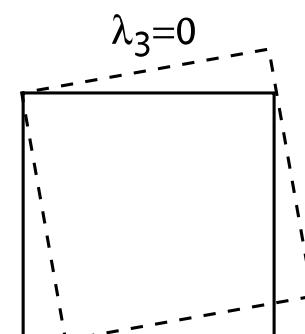
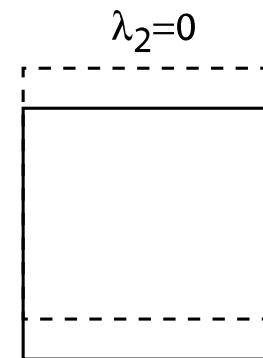
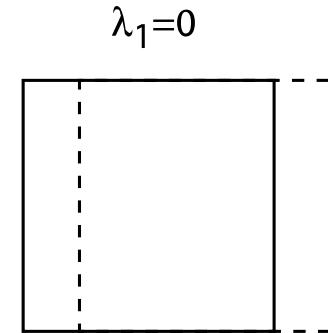
How can the local stiffness matrix be controlled?

- Symmetry
- Diagonal elements are positive
- Controll the rigid-body modes

We have 3 possible ridig body modes

$$\det(\mathbf{k} - \lambda \mathbf{E}) = 0$$

\mathbf{E} denotes the unit matrix

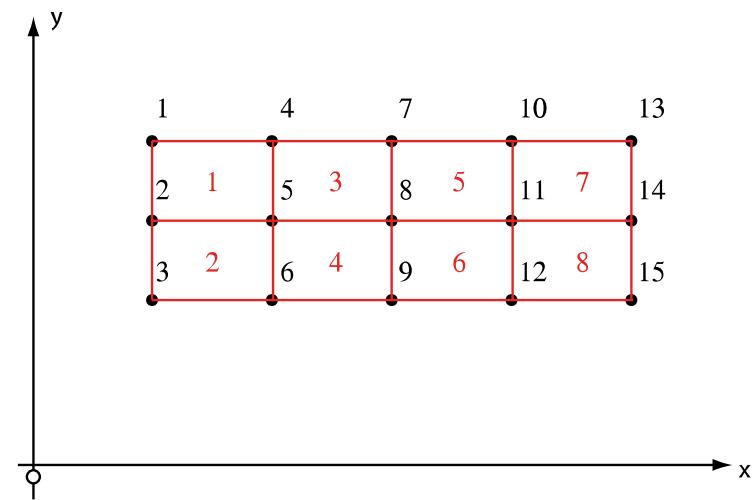
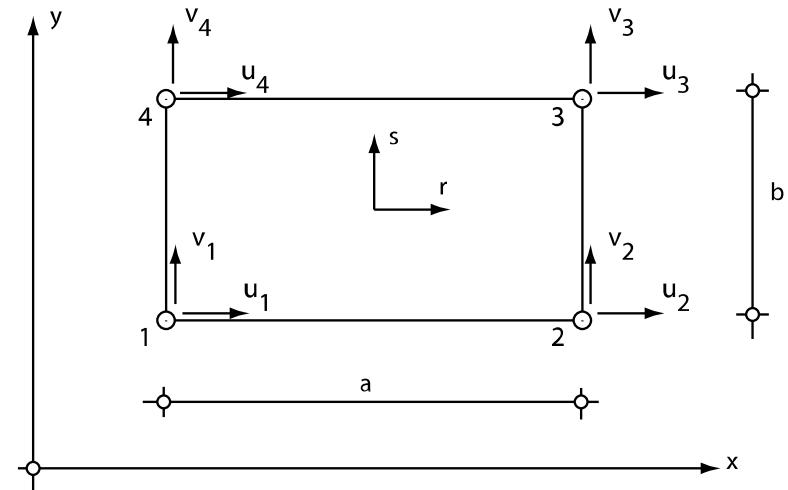


Assembling the global stiffness matrix

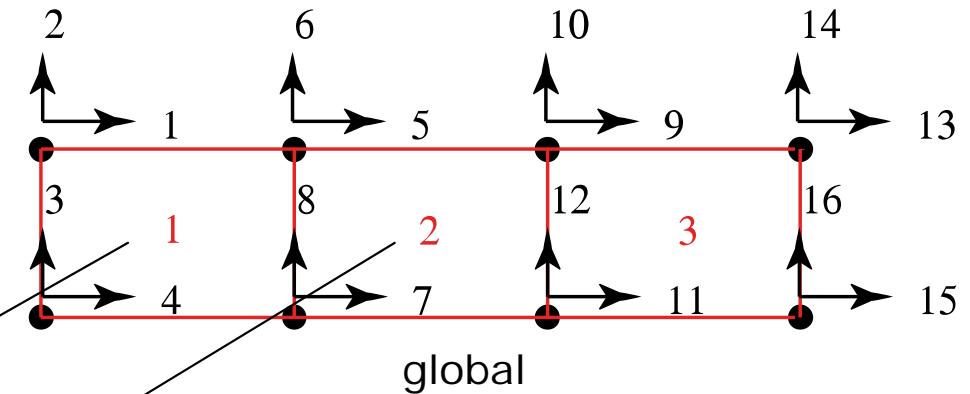
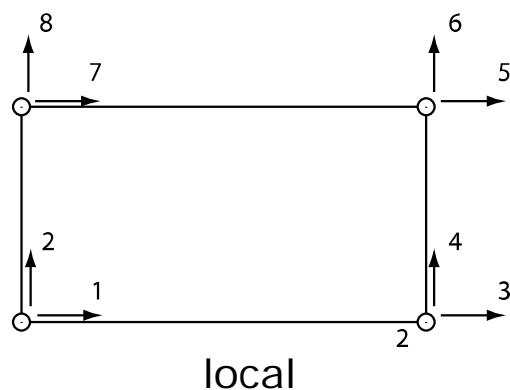
Local stiffness – local coordinates

Global coordinates – global stiffness

Transformation local - global



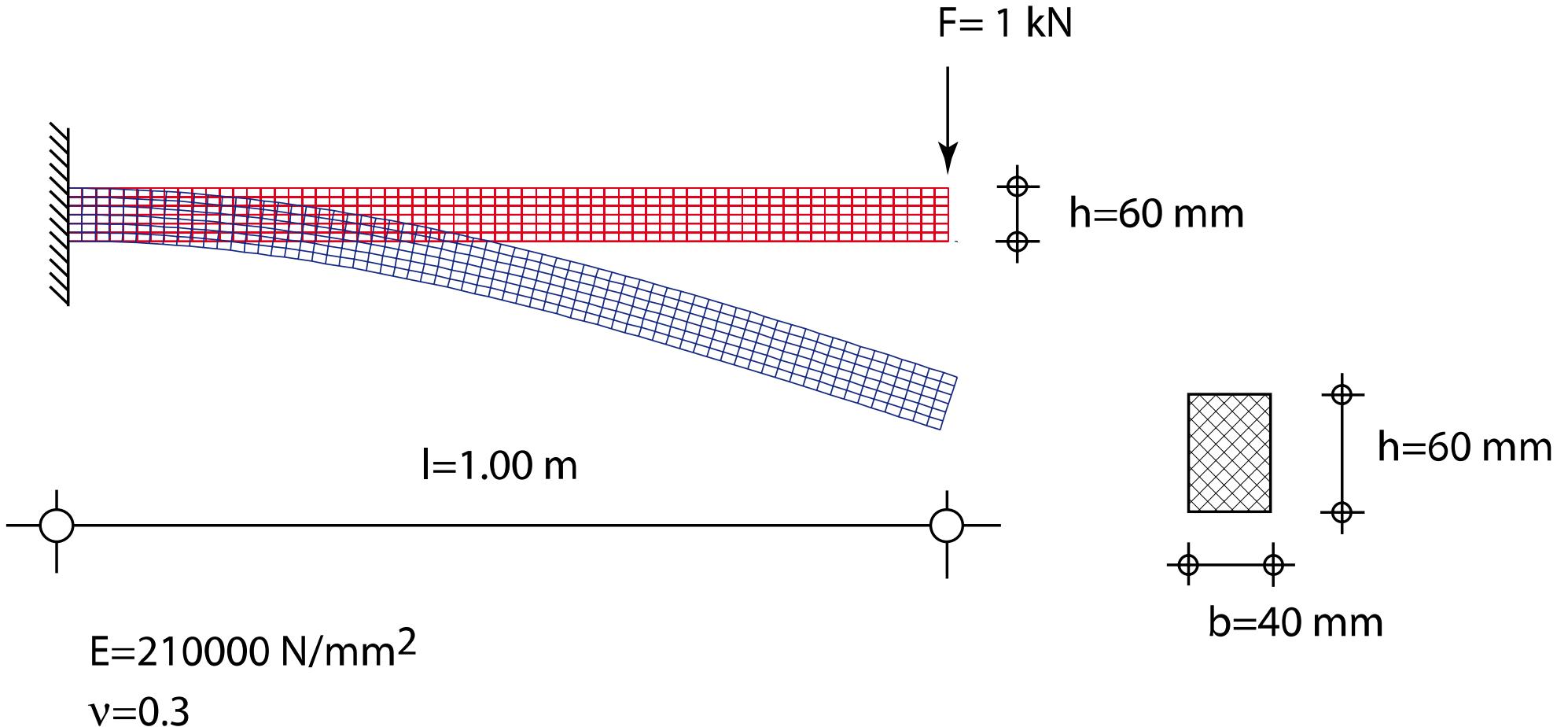
Assembling the global stiffness matrix



$$k_{\text{global}}(5,5) = k_{\text{local}}(5,5) + k_{\text{local}}(7,7)$$

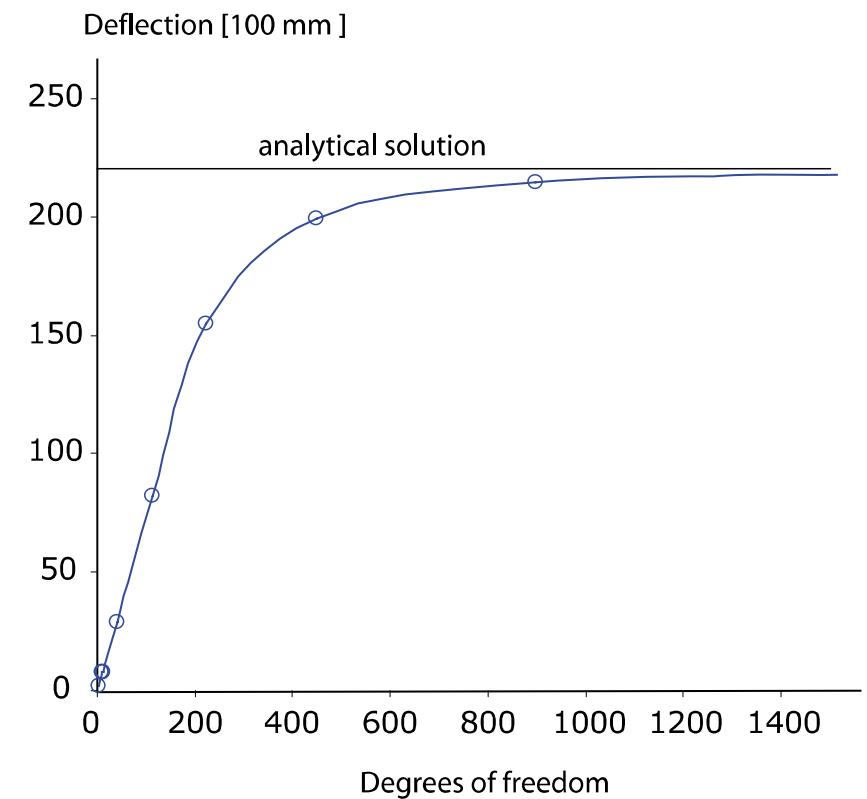
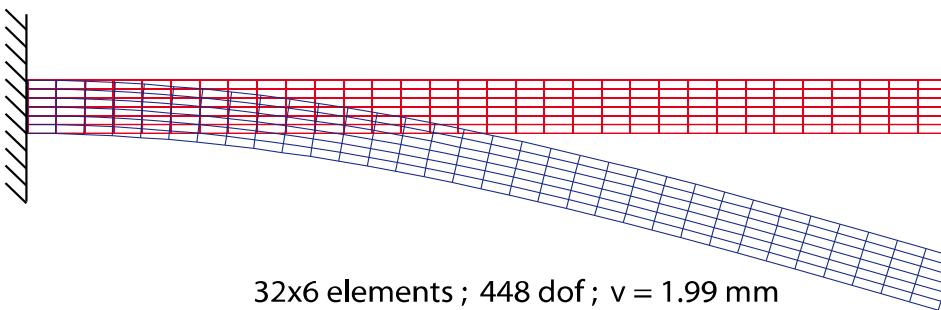
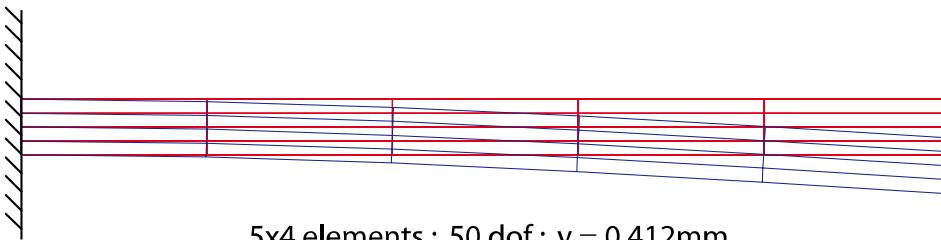
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
1	6.54E+06	-1.50E+06	-5.71E+06	-1.15E+05	2.44E+06	1.15E+05	-3.27E+06	1.50E+06	0	0	0	0	0	0	0	0
2	-1.50E+06	1.73E+07	1.15E+05	-1.70E+07	-1.15E+05	8.35E+06	1.50E+06	-8.64E+06	0	0	0	0	0	0	0	0
3	-5.71E+06	1.15E+05	6.54E+06	1.50E+06	-3.27E+06	-1.50E+06	2.44E+06	-1.15E+05	0	0	0	0	0	0	0	0
4	-1.15E+05	-1.70E+07	1.50E+06	1.73E+07	-1.50E+06	-8.64E+06	1.15E+05	8.35E+06	0	0	0	0	0	0	0	0
5	2.44E+06	-1.15E+05	-3.27E+06	-1.50E+06	0	0	-1.14E+07	0	2.44E+06	1.15E+05	-3.27E+06	1.50E+06	0	0	0	0
6	1.15E+05	8.35E+06	-1.50E+06	-8.64E+06	0	3.46E+07	0	-3.40E+07	-1.15E+05	8.35E+06	1.50E+06	-8.64E+06	0	0	0	0
7	-3.27E+06	1.50E+06	2.44E+06	1.15E+05	-1.14E+07	0	1.31E+07	0	-3.27E+06	-1.50E+06	2.44E+06	-1.15E+05	0	0	0	0
8	1.50E+06	-8.64E+06	-1.15E+05	8.35E+06	0	-3.40E+07	0	3.46E+07	-1.50E+06	-8.64E+06	1.15E+05	8.35E+06	0	0	0	0
9	0	0	0	0	2.44E+06	-1.15E+05	-3.27E+06	-1.50E+06	1.31E+07	0	-1.14E+07	0	2.44E+06	1.15E+05	-3.27E+06	1.50E+06
10	0	0	0	0	1.15E+05	8.35E+06	-1.50E+06	-8.64E+06	0	3.46E+07	0	-3.40E+07	-1.15E+05	8.35E+06	1.50E+06	-8.64E+06
11	0	0	0	0	-3.27E+06	1.50E+06	2.44E+06	1.15E+05	-1.14E+07	0	1.31E+07	0	-3.27E+06	-1.50E+06	2.44E+06	-1.15E+05
12	0	0	0	0	1.50E+06	-8.64E+06	-1.15E+05	8.35E+06	0	-3.40E+07	0	3.46E+07	-1.50E+06	-8.64E+06	1.15E+05	8.35E+06
13	0	0	0	0	0	0	0	2.44E+06	-1.15E+05	-3.27E+06	-1.50E+06	6.54E+06	1.50E+06	-5.71E+06	1.15E+05	
14	0	0	0	0	0	0	0	1.15E+05	8.35E+06	-1.50E+06	-8.64E+06	1.50E+06	1.73E+07	-1.15E+05	-1.70E+07	
15	0	0	0	0	0	0	0	-3.27E+06	1.50E+06	2.44E+06	1.15E+05	-5.71E+06	-1.15E+05	6.54E+06	-1.50E+06	
16	0	0	0	0	0	0	0	1.50E+06	-8.64E+06	-1.15E+05	8.35E+06	1.15E+05	-1.70E+07	-1.50E+06	1.73E+07	

Example

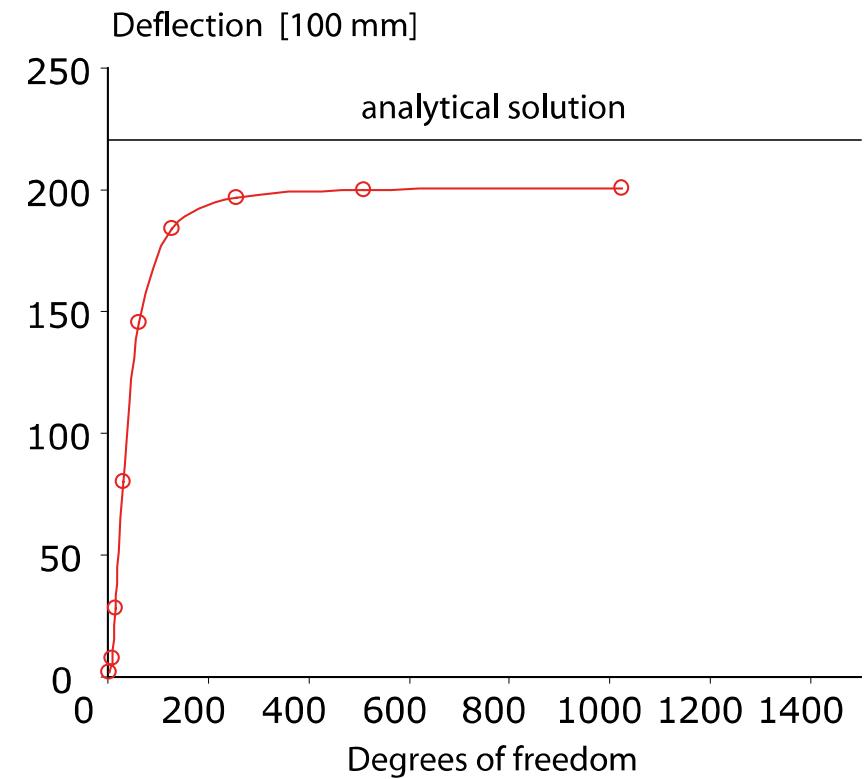
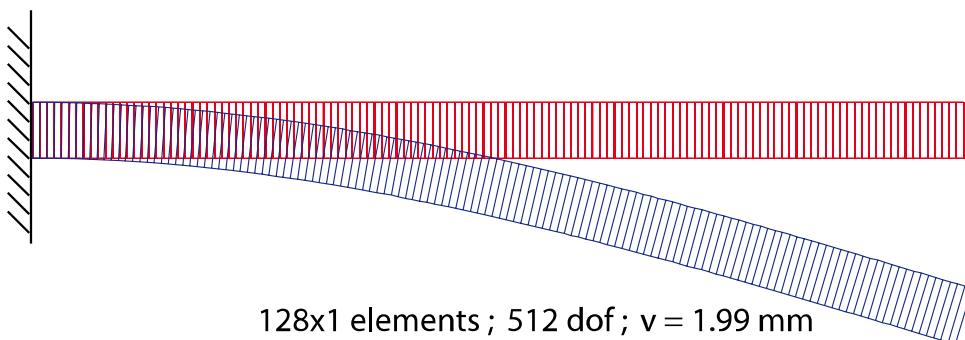
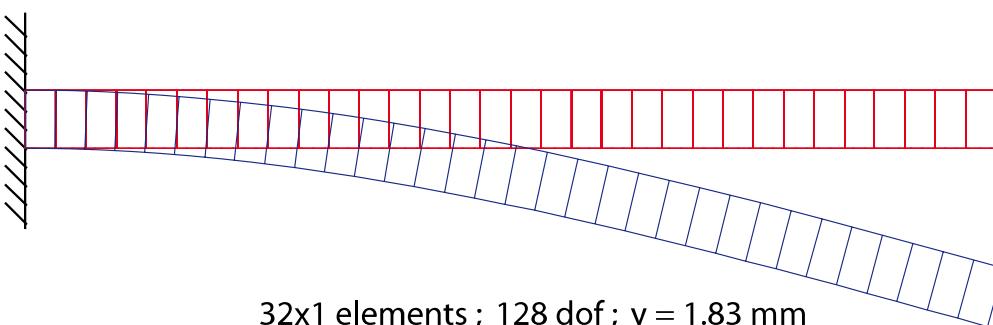
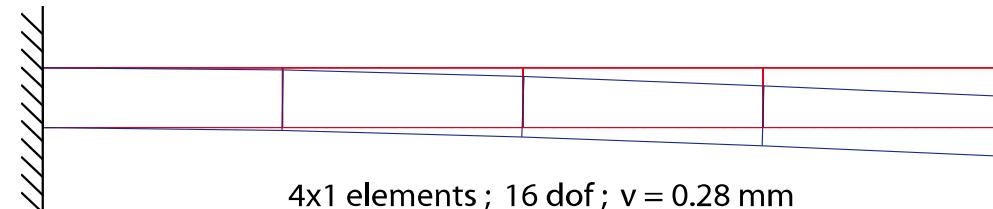


The Matlab-Code will be provided on
our Web site

Results



Results



Stress

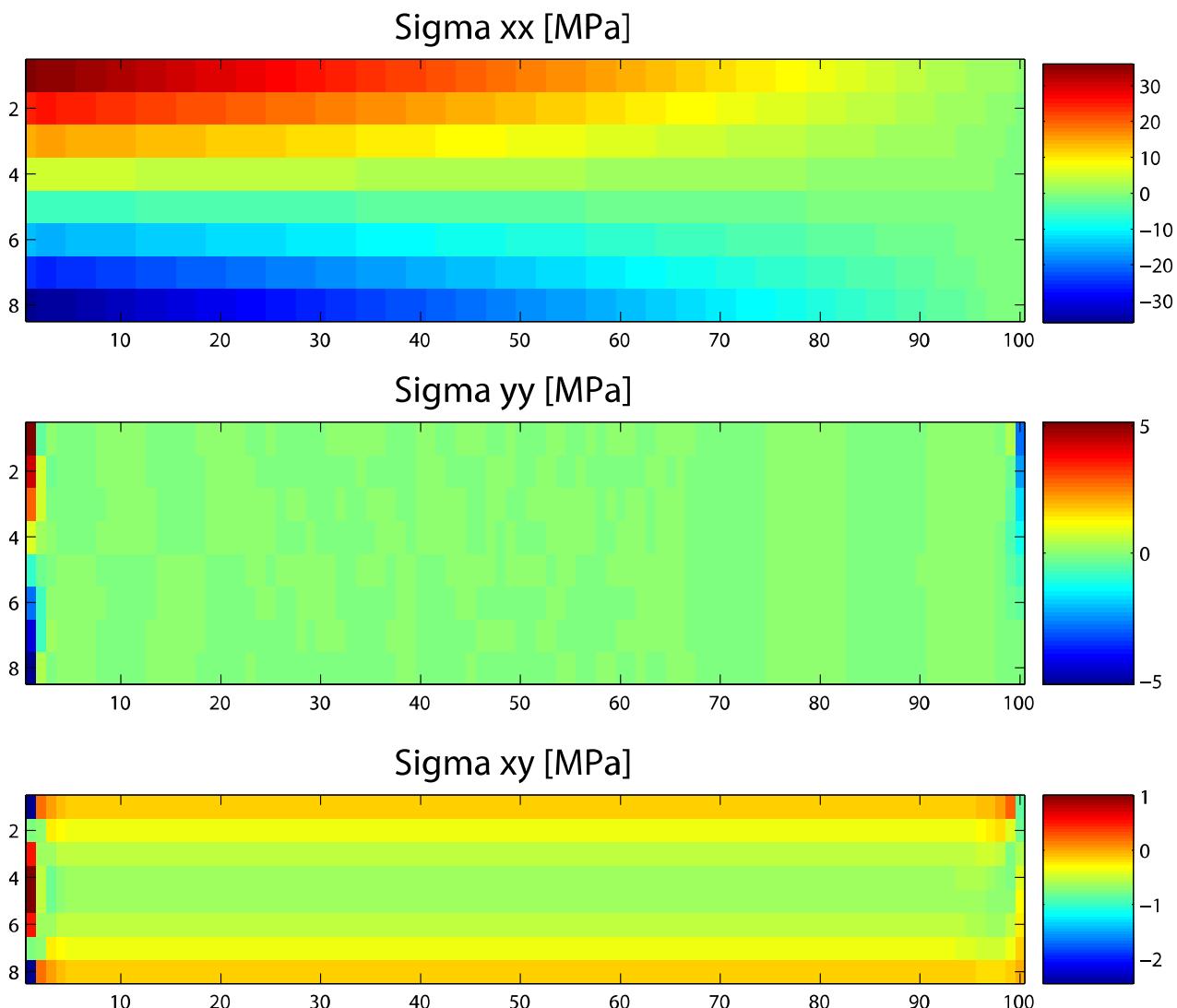
$$\begin{bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{bmatrix} = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & 0.5(1-\nu) \end{bmatrix} \mathbf{B} \mathbf{V}$$

Displacement of the element

Transformation of the global displacement into local displacements

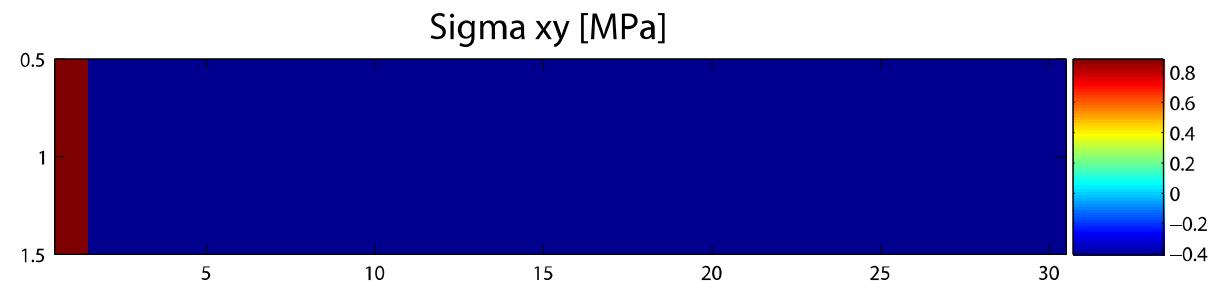
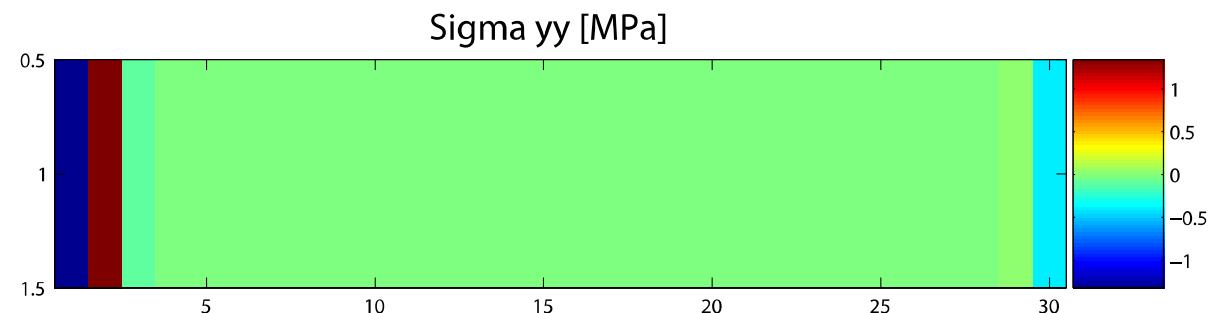
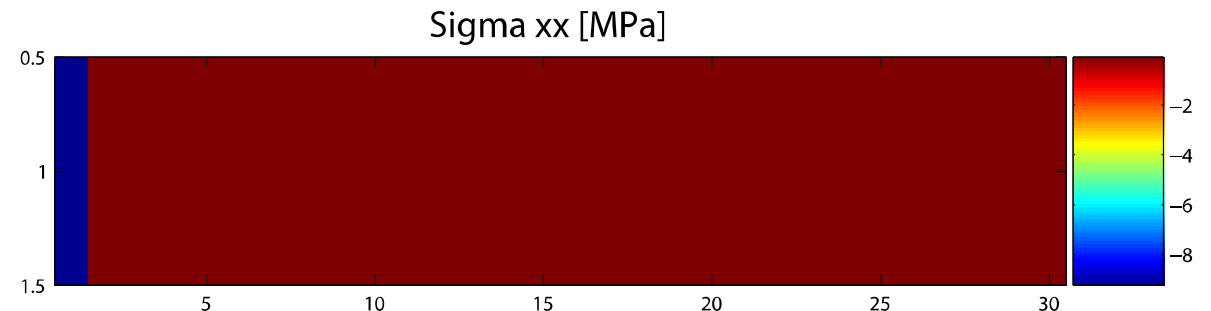
Stress

100x8 Elements



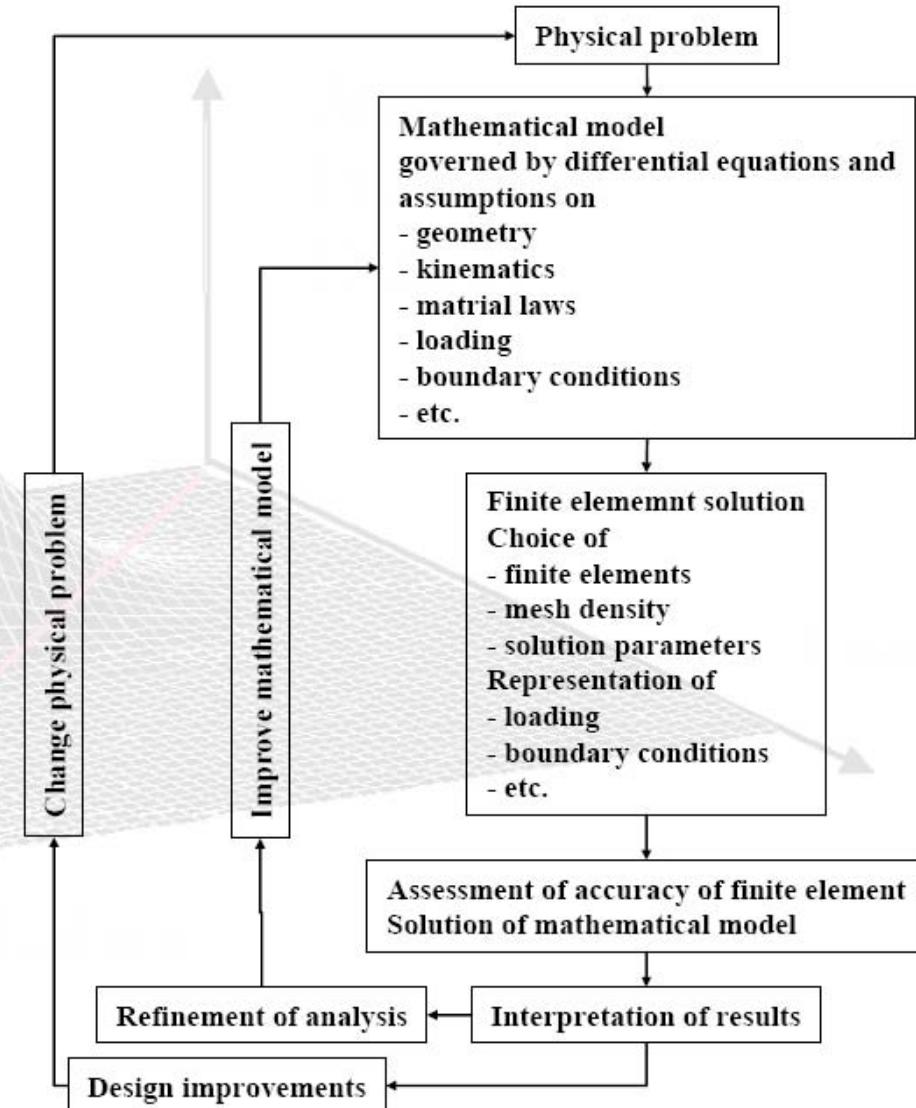
Stress

20x1 Elements

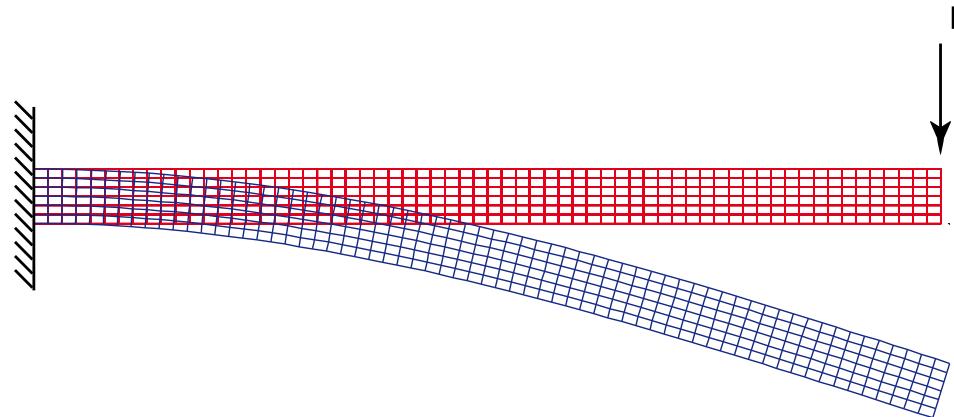


Introduction to the use of finite element

- **Physical problem, mathematical modeling and finite element solutions**
 - we are only working on the basis of mathematic models !
 - choice of mathematical model is crucial !
 - mathematical models must be *reliable and effective*



The Finite Element Method and the Analysis of Systems with Uncertain Properties



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ETH – Zürich
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